Non-Halters in the Busy Beaver Problem

presented by Owen Kellett 4 April 2003

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The Busy Beaver Problem

"Consider, for a fixed positive integer *n*, the class K_n of all the *n*-card [state] binary Turing machines ... Let *M* be a Turing machine in this class K_n . Start *M*, with its card 1, on an all-0 tape. If *M* stops after a while, then *M* is termed a valid entry in the BB-n contest ... and its score $\sigma(M)$ is the number of 1's remaining on the tape at the time it stops ... [the set of σ -values] has a (unique) largest element which we denote by $\Sigma(n)$... It is practically trivial that this function $\Sigma(n)$ is not general recursive ... [but] it may be possible to determine the value of $\Sigma(n)$ for particular values of *n*."

-Lin & Rado "Computer Studies of Turing Machine Problems" Journal of the Association for Computing Machinery, Vol. 12, No. 2 (April, 1964), pp. 196-212

Problem: How do we know when it stops?

- Turing Machine halting problem:
 - Turing Machine M
 - Input tape w
 - Function : given any TM *M* and any Input tape *w*, return whether or not *M* halts on *w*.
 - This function does not exist
- However!
- Certain routines can be defined which identify whether or not a particular machine exhibits a specific non halting behavior
- The Busy Beaver problem exhibits several recognizable behaviors

Backtracking





Subset Loops



- A Turing Machine M is classified as a subset loop if
 - There is a set of states S such that every possible transition from each state in S is defined
 - Every transition defined from a state in S is a transition to another state in S
 - During execution, at some point the machine enters one of the states in S



- A machine is classified as a simple loop if (given words of arbitrary length X, Y, V, and C and state s):
 - The following tape configuration is reached: $0^{(C]}[X_s][Y]0^*$

-and one of the following-

- The same tape configuration is reached at a later point

-or-

- The following tape configuration is reached at a later point: 0*[C][V][X_s][Y]0*
- Between these points, the read head never moves past the left edge of the initial X
- The corresponding mirror of the above specification also identifies a simple loop

-Machlin and Stout. "The Complex Behavior of Simple Machines" Physica D 42 (1990). pp. 85-98

Example: Simple Loop

- 0 State 0 1 State 1 10 State 2 10**0** State 3 100**0** State 4 1000**0** State 5 ate 5 0* [Y] [X] [C] 0* ate 5 0000 State 5 10000 State 5 010000 State 3 State 4 010000 **0**10000 State 2 010000 State 3 **0**10000 State 1 **0**010000 State 0 **1**010000 State 1 1010000 State 2 1010000 State 3 1**0**10000 State 1 **1**010000 State 0 **0**1010000 State 4 0**1**010000 State 5 **0**1010000 State 3 01010000 State 4 01010000 State 2 **011**0**0**00 State 3 01010000State 1 ftate 0 0* [Y] [X] [V] [C] 0* ltate 1 Jtate 2 State 3 10**1**010000 1**0**1010000 State 1 **1**01010000 State 0
- The tape configuration of the most recent occurrence of each <state, symbol> pair is saved
- This particular instance is the pair <4,1>
- Example machine is a mirror version of the simple loop specification
- The next tape configuration of <4,1> is compared to the previous
- In this case, all components are identifiable and match
- Location of read head is in same relative location
- The read head never moves to the right of the original X (remember this is a mirror simple loop)
- All conditions are satisfied, machine is a simple loop non-halter

Christmas tree non-halter sweeps back and forth across the

•	In the general	sense, a christmas tre	ee non-halter sweeps back and t	orth a
	tape in a repe	atable manner:	1 101010 Sta	te 1
			1 1 01010 Sta	te 2
	0	State 0	/ 11 0 1010 Sta	te O
	1	State 1	/ 11 1 1010 Sta	te 1
	10	State 2	/ 111 1 010 Sta	te 2
				⊥ - ^



111 0 10	State	3	/
11 1 010	State	3	
1 1 1010	State	0	
1 0 1010	State	3	/
1 01010	State	3	/
0 101010	State	0	

TTTT N TOTO	ыаге	υ
1111 1 1010	State	1
11111 1 010	State	2
111111 0 10	State	0
111111 1 10	State	1
1111111 1 0	State	2
11111111 0	State	0
11111111 1	State	1
111111111 0	State	2

Christmas Tree Detection: Step 1

0* [U] [V] 0*	s=2
1110	State 2
11 1 0	State 3
1 1 10	State 0
1 0 10	State 3
1 010	State 3
0 1010	State 0
1 1010	State 1
1 1 010	State 2
11 0 10	State 0
11 1 10	State 1
111 1 0	State 2
1111 0	State 0
1111 1	State 1
111110	State 2
0* [U] [X] [V] 0*	s=2

• The tape exhibits a back and forth sweeping motion

- After one sweep, the tape has the following configuration:
 - $0^{*}[U][V_{s}]0^{*}$

 After the next sweep, a new middle part, and the same end parts are seen:
– 0*[U][X][V_s]0*

Christmas Tree Detection: Step 2

	1111	110	State	2		The machine alters the t	ape	e accordir	ng	
	1111	110	State	3		to the following gramma			-	
	11 <mark>1:</mark>	1 10	State	0		$- [X][V_s] \rightarrow {}_{q}[X'][V']0^*$				
	11 <mark>1(</mark>) 10	State	3		$- [X_{a}][X'] \rightarrow [X'][Y]$				
	11 <mark>1(</mark>	010	State	3		$- 0^{*}[U_{n}][X'] \rightarrow 0^{*}[U'][Y']_{n}$				
	111(010	State	0	\backslash	$- [Y'][Y] \rightarrow [Z][Y']$				
	1010	010	State	3 🔨	\backslash	$[\downarrow] I_{\Gamma} \downarrow] \downarrow [\Box] I_{\Gamma} \downarrow]$				
	1 01(010	State	3		$- [[1]]_{r} \vee] \rightarrow [2][\vee_{s}]$				
0	1010	010	State	0			•	U = 11	•	s = 2
1	1010	010	State	1	<hr/>	0*[U][X][V _s]0*		V - 10	•	a – 0
1:	1 01(010	State	2	\mathbf{n}			V = 10	•	q = 0
1	1010	010	State	0		0*[U_][X'][V']0*	•	X = 11	•	r = 2
1	1 1 1(010	State	1			•	X' = 10		
1	11 1 (010	State	2			•	V' = 10		
1	111(010	State	0		0*[U'][Y'][_r V']0*	•	U' = 111		
1	1111	110	State	1				$\nabla' = 11$		
1:	1111	110	State	2		0*[U'][Z][V'' _s]0*				
1	111	110	State	0	/		•	∠ = 11		
1	111	111	State	1			•	V'' = 110		
1:	111	111(0 State	2						

• The following holds:

 $- 0^{*}[U'][Z][V''s]0^{*} = 0^{*}[U][X][X][Vs]0^{*}$

[11111110] [11111110]

C	hris	tma	S	Tre	e Detec	tion:	Step	3	
1111	1110	State	2	•	The mechine off	ara tha ta			
1111	1110	State	3	•	The machine all	ers the ta	pe accordir	ig	
1111	1 1 10	State	0		to the following (grammar			
1111	1 0 10	State	3		$- [X][V_s] \rightarrow [X']$	[V']0*			
11111	1 010	State	3		$- [X_{a}][X'] \rightarrow [X']$][Y]			
1111	1010	State	0		$-$ 0*[U ₀][X'] \rightarrow 0 [*]	*[U'][Y'],			
1110	1010	State	3	\mathbf{N}	$- [Y'][Y] \rightarrow [Z][Y]$	(']			
11 1 0	1010	State	3		$- [Y'][V'] \rightarrow [7][V']$	V'' 1			
1110	1010	State	0			Y SJ			
1010	1010	State	3	\mathbf{k}		, •	• U = 11	•	s = 2
1 010	1010	State	3		0*[U][X][X][V _s]0*		• V = 10	•	$\mathbf{q} = 0$
0 1010	1010	State	0			į l	X = 11	•	r – 2
1 1010	1010	State	1	$\langle \rangle$			X = 11	•	1 – 2
1 1 010	1010	State	2		0*[U_][X'][Y][V']0*		• X = 10		
11 0 10	1010	State	0]	• V' = 10		
11 1 10	1010	State	1		0*[U'][Y'][_r Y][V']0*	•	• U' = 111		
111 1 0	1010	State	2] •	• Y' = 11		
1111 0	1010	State	0				7 – 11		
1111 1	1010	State	1		0*[U'][Z][Z][V'' _s]0*		2 - 11		
111111	1010	State	2		/]	v = 110		
111111	1 0 10	State	0				• Y = 10		
111111	1 <mark>1</mark> 10	State	1						
11111	1110	State	2	•	The following holds	:			
11111	1110	State	0		– 0*[U'][Z][Z][V''s	$0^* = 0^*[U][$	X][X][X][Vs]0*		
111111	111 1	State	1		[1111111110)] [11 ⁻	11111110]		
11111	11110	State	2						

Alternating Christmas Trees

• The machine transforms the tape much like a normal Christmas tree, however, it takes two sweeps across the tape rather than one to complete one cycle

Christmas Trees	Alternating Christmas Trees
0*[U][X][X][X][V]0*	0*[U][X][X][X][V]0*
0*[U'][Y][Y][Y][V']0*	0*[U'][Y][Y][Y][V']0*
0*[U'][Z][Z][Z][V'']0*	0*[U'][Z][Z][V'']0*
D*[U][X][X][X][X][V]0*	0*[U"][M][M][V""]0*
	0*[U''][N][N][N][V'''']0*

Busy Beaver Non-Halters

	n = 3		n = 4		n = 5	
backTrack	817	82.1106%	47102	85.1538%	3842187	87.1350%
subsetLoop	17	1.7085%	749	1.3541%	38761	0.8790%
simpleLoop	159	15.9799%	7243	13.0943%	508156	11.5242%
christmasTree	2	0.2010%	198	0.3580%	18012	0.4085%
alternateChristmasTree	0	0.0000%	23	0.0416%	2818	0.0639%
holdout	0	0.0000%	5	0.0090%	2623	0.0595%
total	995		55314		4409466	

*Note: Machines are classified according to the first routine which tests positive. The detection routines are applied in succession from top to bottom for each individual machine.

B4 Holdouts

- Two of the holdouts of the B4 exhibited the one other behavior specified by Brady but not yet implemented as a detection routine for this project
- These machines mimic binary counters by altering the tape in such a way that it progressively counts in binary format



B4-counter1



B4-counter2

	B4-Cou	nter1	Execut	ion
0	State 0	10001	State 0	
1	State 1	/100 0 1	State 1	
10	State 2	/ 10 0 01	State 1	
10 0	State 3	/ 10001	State 1	
101	State 0	/ 1 0001	State 1	
101	State 1	1 0 001	State 2	
1 01	State 1	10 0 01	State 3	
101	State 2	10 <mark>101</mark>	State O	
10 1	State 3	1 0 101	State 1	*Note: this machine
10 0	State 2	1 0101	State 1	generates binary
100 0	State 3	1 0 101	State 2	numbers that read
1001	State 0	10 1 01	State 3	from right to left
10 0 1	State 1	10001	State 2	rather than the
1 0 01	State 1	10001	State 3	
1 001	State 1	10 <mark>01</mark> 1	State O	right
1 0 01	State 2	10011	State 1	
10 0 1	State 3	1 0 011	State 1	
10 <mark>1</mark> 1	State 0	1 0011	State 1	
1011	State 1	1 0 011	State 2	
1 011	State 1	10011	State 3	
1011	State 2	10 <mark>1</mark> 11	State O	
10 1 1	State 3	10111	State 1	
10 0 1	State 2	1 0111	State 1	
100 1	State 3 /	10111	State 2	
100 0	State 2/	10 1 11	State 3	
1000 0	State $3'$	10 0 11	State 2	

B4 Holdouts

• Two of the holdouts are very similar to alternating christmas trees



0	State	0
1	State	1
10	State	2
10 0	State	3
1 0 0	State	1
1 00	State	0
0 100	State	0
1 100	State	1
1 1 00	State	2
11 0 0	State	1
1 1 00	State	0
1 10 <mark>0</mark>	State	0
0 1100	State	0
1 110 <mark>0</mark>	State	1
1 1 10 <mark>0</mark>	State	2
11 1 00	State	1
111 0 0	State	2
1110 <mark>0</mark>	State	3
111 0 0	State	1
11 1 00	State	0
1 1 10 <mark>0</mark>	State	0
1 110 <mark>0</mark>	State	0
0 1110 <mark>0</mark>	State	0
1 1110 <mark>0</mark>	State	1
1 1 110 <mark>0</mark>	State	2
11 1 10 <mark>0</mark>	State	1
111 1 00	State	2
1111 0 0	State	1

B4-uneven Alternate Christmas Tree1 Execution

- Recognizable alternating sweeping motion as seen in alternating Christmas trees
- Right boundary of intermediate sweep does not at least reach the right boundary of the previous major sweep
- Current implementation assumes that each sweep spans at least as far as the previous sweep
- Only minor modifications to the alternating Christmas tree routine should be necessary to account for this behavior

B4 Holdouts

• The final holdout escapes the Christmas tree detection routine because of unusual startup effects



0	State	0
1	State	1
10	State	1
10 0	State	2
1 0 0	State	2
1 00	State	2
0 100	State	3
0 0100	State	0
1 0100	State	1
1 0 100	State	1
10 1 00	State	2
1 0 100	State	3
1 01 <mark>00</mark>	State	0
0 10100	State	0
1 10100	State	1
1 1 0100	State	1
11 0 100	State	1
110 1 00	State	2
11 0 100	State	3
1 1 0100	State	0
1 10100	State	0
) 1101 <mark>00</mark>	State	0
L 1101 <mark>00</mark>	State	1
L 1 101 <mark>00</mark>	State	1
L1 1 01 <mark>0</mark> 0	State	1
L11 0 1 <mark>0</mark> 0	State	1
L110 1 00	State	2

B4-startup Effects Christmas Tree1 Execution

- The Christmas tree detection routine runs the machine for a hundred transitions or so before looking for Christmas tree behavior to account for startup effects
- These transitions, however, are still observed to establish left and right boundaries for each sweep of the tape
- This machine creates a false right boundary during the startup phase
- Again, only minor modifications to the Christmas tree routine should be necessary to account for this behavior

Future Work

- Counter detection routines
 - Brady goes into more detail regarding the behavior of Counters, specifying a grammar in the same format as the Christmas tree grammar
 - Also mentions Counter variations (unary, binary, base-3, etc.)
- Christmas tree variations
 - Account for startup effects shown in B4 holdout
 - Uneven alternating Christmas trees
 - Multi-sweep (3,4,5... sweeps) alternating Christmas trees (seen in several of the random B5 holdouts that I've looked at)
 - Several more